

The Cairns Tilt-Train Derailment in Queensland

An Overview and Partial Analysis

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Scope of This Commentary

- I do not propose a full analysis of the accident here
- After performing a WBA from the information in the accident report, I raise questions concerning
 - the incomplete consideration of all possible causes of the driver's failing to slow the train
 - The adequacy of the existing protection systems, in particular for the accident location

The Brisbane-Cairns Tilt Train

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The Cairns Tilt Train



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A (Prototype?) Power Car



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The Cairns Tilt Train

- Narrow gauge
 - 1067 mm gauge, similar to that of many streetcar systems
- Takes just over 25 hours for the 1,681 km journey
 - Previous journey time 32 hours
- „High speed“
 - 160 kph maximum speed
- Diesel
 - DMU sets: *City of Cairns* and *City of Townsville*
 - Two EMU sets also operate Brisbane-Rockhampton, which is electrified
 - **Note:** the EMUs have lower C of G (CoG) than the DMUs!

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The Route



The Tilt Train Underway



The Tilt Train Underway



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Whoops! (November 2004)



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The Berajondo Derailment

What Happened, in Brief 1

- Acronym soup ahead! All that I use are defined here
 - The Cairns Tilt Train (**CTT**) *City of Townsville* (**CoT**), a Diesel Multiple Unit (**DMU**), derailed at Cabbage Tree Creek (**CTC**) at 23:55 Australian Eastern Standard Time (**EST**) on 15.11.2004 between Berajondo (**BO**) and Baffle (**BA**) on the Bundaberg-to-Gladstone part of the route from Brisbane to Cairns.

What Happened, In Brief 2

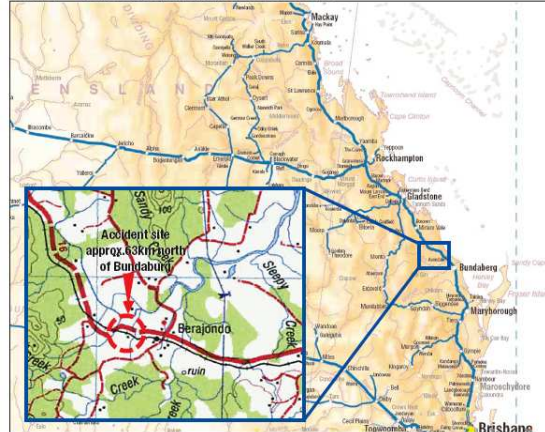
- Point of Derailment (**POD**) was 83 **m** beyond the Speed Board (**SPB**) restricting the **CTT** to 60 **kph**. It was travelling at 112 **kph** at the **POD**.
- This 60-kph **SPB** was 415 **m** beyond the Mid-Section Magnet (**MSM**)
- The **MSM** lies 1.212 **km** beyond a 150-kph **SPB**.
- The **MSM** lies 3.525 **km** beyond the Station Protection Magnet (**SPM**) at **BO** and 3.014 **km** before the **SPM** at **BA**.
- On the 1.6 **km** stretch from the 150-kph **SPB** to the 60-kph **SPB**, the **CTT** had accelerated from 80 **kph** to 111 **kph** under steady power.

Derailment and Harm (people)

- The train derailed
 - close to midnight
 - dark night (no moon)
 - single-track line (as most of the way)
 - block („section“) ran between the stations **BO** and **BA**
 - Light signals at stations: in particular for entry and departure
- 0 killed; 18 severe, 10 moderate, many light, injuries
- Problems during evacuation
 - Train collided with electrification infrastructure
 - Not knowable what was „live“ and what not

Derailment Location

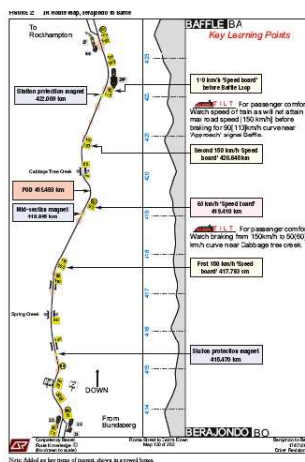
FIGURE 1: Location of Berajondo Accident Site, Queensland



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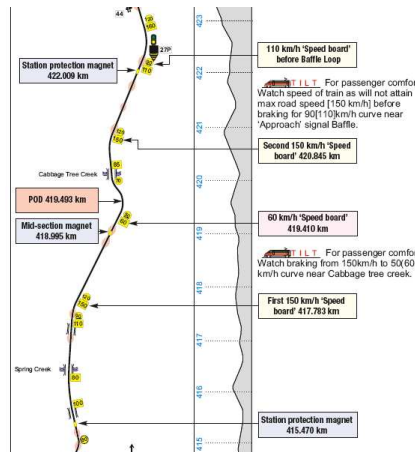
The Berajondo to Baffle Route Map



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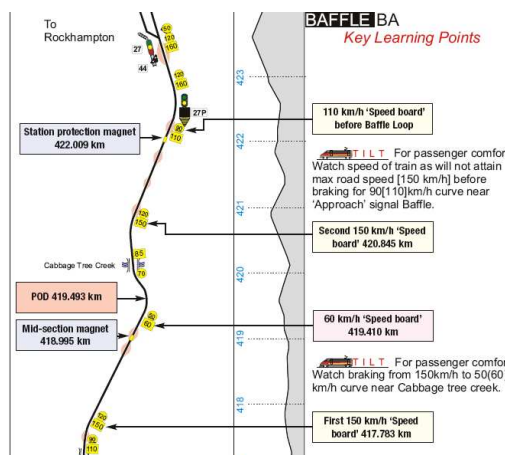
The Route Map Around the Derailment



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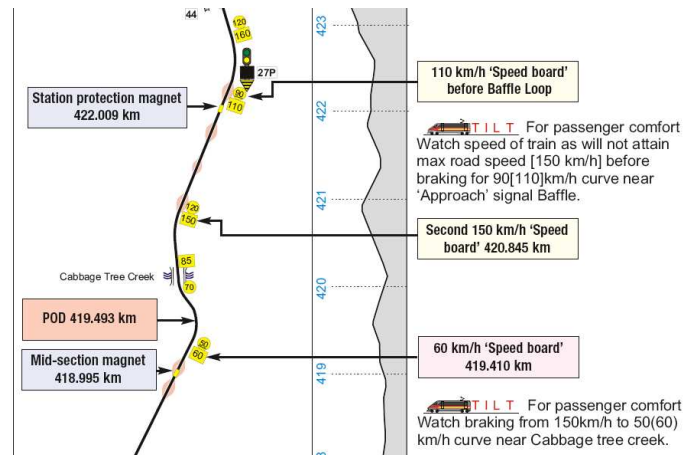
The Route Map at the Point of Derailment



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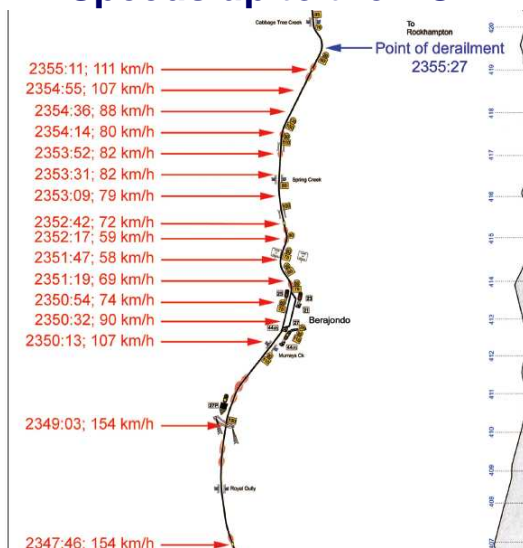
The Point of Derailment



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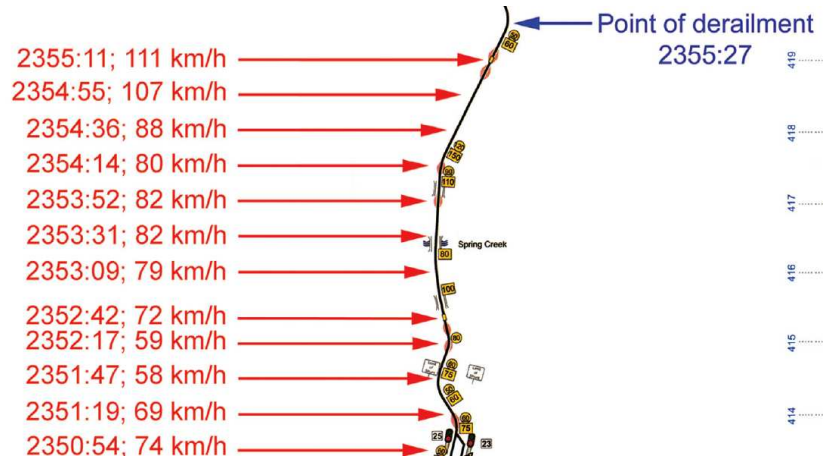
Speeds up to the POD



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Speeds Immediately Before Derailment



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Derailment Dynamics

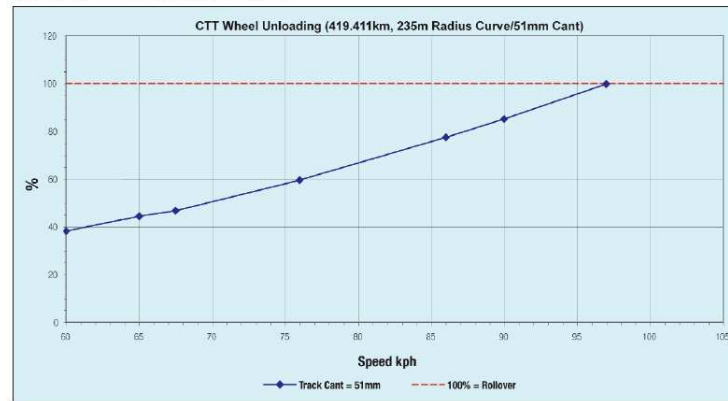
- The train was travelling at 112 kph at POD
- The left-hand curve at CTC was posted for 60 kph for the Tilt Train (50 kph for others)
- Tipover: full wheel unloading for lead power car of DMU at CTC would have occurred at about 97 kph
 - post-accident modelling with *Vampire* (Sec 2.6)

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Tilt Train Tips

FIGURE 14: Wheel Unloading vs Speed



The Result



An Aerial View

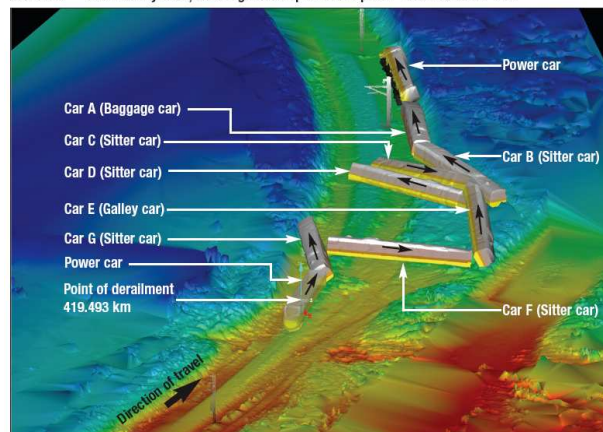


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A Laser-Measurement Reconstruction

FIGURE 9: Laser survey scan, showing relative position of power cars and trailer cars



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Rear View Showing Speedboard



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Selected Pertinent Facts 1

- No technical problem with train or infrastructure
- Two drivers; one had left cab to prepare coffee
 - Operationally allowed for non-driving driver to leave cab
- Signals
 - Light signals at Berajondo and Baffle stations
 - Speed boards, at which the train has already to be at or below indicated speed
- Other indicators
 - Station protection magnets at BO and BA
 - Mid-section magnet 498 m before POD
 - triggers a cab alarm which must be acknowledged, and was!

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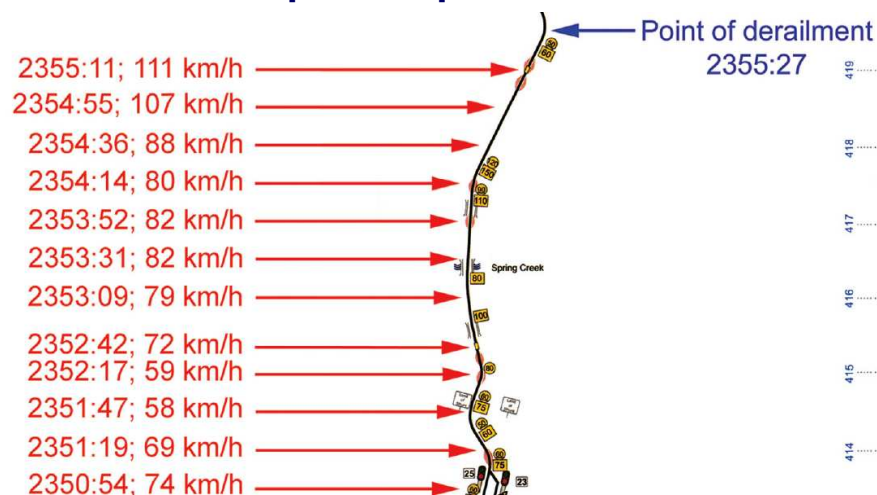
Selected Pertinent Facts 2

- One block from BO to BA
 - block occupied by the CTT at the time
- Before BO, CTT had attained 154 kph and then slowed as required
- Driver had maintained at or below posted speed up to (83 m before) POD
 - after BO, 74 kph → 58 kph → 111 kph
 - After BO SPM, 72 kph → 111 kph
 - After 150-kph speed board, 80+ kph → 111 kph
 - Note: train is physically unable to attain 150 kph in this short 1.627-km segment before the CTC 60-kph speed board
 - did not slow at MSM

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Speeds up to POD



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Causes?

- Pretty clear: cause was derailment at excessive speed (Report Sec 2.8, 3.1 Major Factor 1)
- That means, in the absence of automatic protection systems, that for better or for worse the driver is causally implicated
- So what on earth was going on?
 - We shall consider this after seeing the WBG

Report Conclusions

Report Conclusions: Major Factors

- 1. Accident principally caused by excessive speed
- 2. The driver did not reduce the train to a safe speed before entering the Cabbage Tree Creek curve
- 3. The train was in steady power „virtually up to“ derailment [*PBL note: to 3 secs before derailment*]
- 4. It is possible that the driver became disoriented and/or distracted from his principal task in this section
- 5. There is no technical system that detects very short periods of driver inactivity/distraction

Report Conclusions: Underlying Factors 1

- 1. At 417.783 km (23:54.26 hours), posted speed increases to 150 kph
- 2. Possible that driver mistook mid-section alarm for station protection magnet before Baffle
- 3. Possible that driver momentarily left driving position, either shortly before or after passing mid-section magnet

Report Conclusions: Underlying Factors 2

- 4. Safe driving of CTT largely depended on
 - driver responding to external prompts
 - speed boards, vigilance-system warnings, station magnet system
 - driver's track knowledge and competency
 - two-driver mode of operation
- 5. Co-driver absent from his seat, not in a position to check driver's ops (operational procedures did not preclude this)
- 6. Train's headlight would only have provided limited visual detail (of distant SPB or CTC curve)

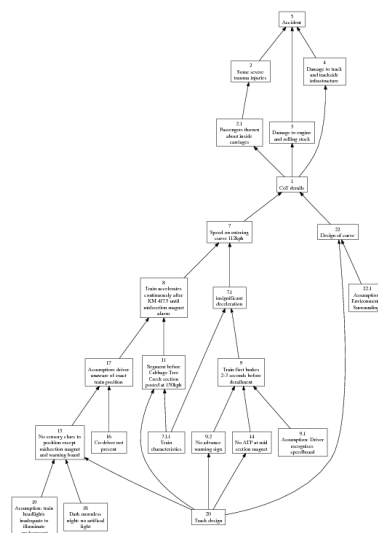
Report Conclusions: Underlying Factors 3

- 7. External darkness may have contributed to loss of geographical awareness
- 8. MSM is primarily used for providing tilt train geographical reference information. It provides no indication of location or next speed limit. A driver who incorrectly assumes the location of the train is not aided by the alarm.
- 9. [Monitoring of driver's return to duties after absence]

The Why-Because Graph

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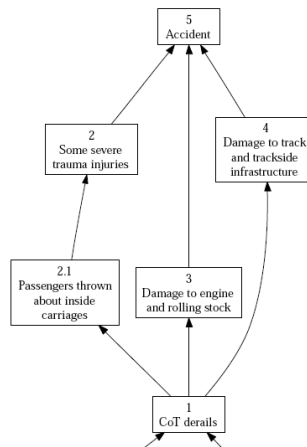
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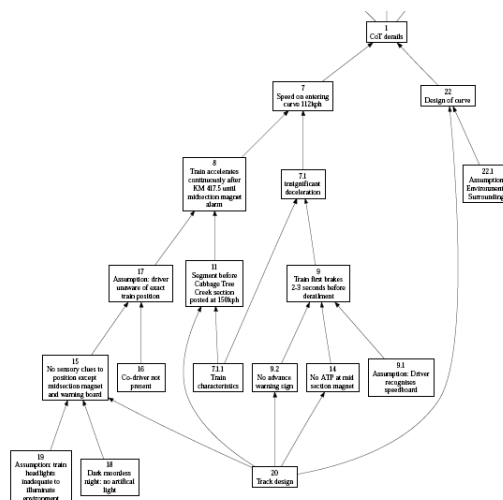
WBG Upper Part: Derailment Consequences



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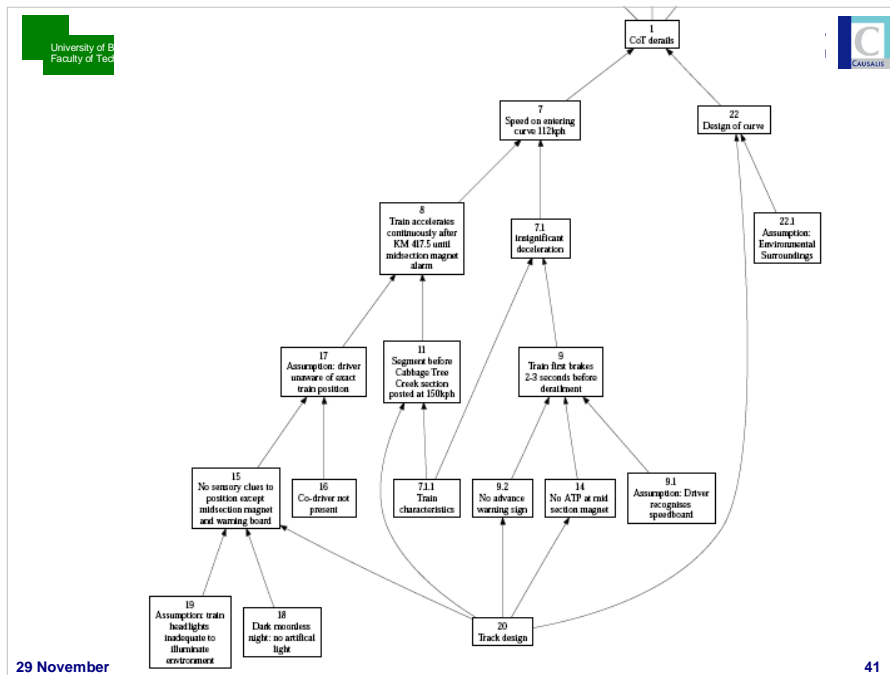
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WBG Lower Part: Causes of Derailment



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RVS
Rechnernetze und
Verteilte Systeme

Observations on the WBG

- The WBG is sparse
 - 23 nodes altogether, 18 nodes precursory to derailment
- However, it does identify significant issues
 - Track design: 5 out-edges!
 - Design of curve (general topography of track in vicinity)
 - 1.627 km segment posted 150 kph followed by posted-60-kph curve
 - MSM 0.415 km before 60-kph SPB
 - Few sensory clues to position
 - SPB and MSM
 - Moonless night. Headlights inadequate?
 - Train
 - accelerated continuously for 4+ km previous to POD
 - braked 2-3 sec before derailment (driver saw 60-kph SPB?)

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General Observations

- Note that this WBG is derived from the report
 - It was not produced through our interpretation of events
- It identifies significant issues
 - Explaining why driver accelerated and failed to slow
 - Acceleration? Obvious: he could accelerate while remaining under posted limits, so why not?
 - Failing to slow? Not so obvious
 - Design of protection systems: adequate?

Observations and Partial Analysis

Two Main Issues from WBG

- 1. Why did driver fail to slow?
- 2. Are the protection systems adequate?

Disclaimer

- Please note: in what follows, I am deriving individual factors
- These factors are not to be thought of as mutually exclusive. It is possible, even likely, that, of the potential factors I identify, more than one of them played a role in the accident
- My purpose in Issue 1 is to enumerate potential factors, and note how (whether) they are handled in the accident report; it is not to propose my own explanation of the accident
- My purpose in Issue 2 is to assess countermeasures

Issue 1: Driver Failed to Slow

Potential Causes of Failing to Slow 1

- Driver distracted, fatigued or incapacitated?
 - Distracted? Maybe (maybe left his seat, Sec 2.8)
 - Fatigued? Probably not (Sec 2.12)
 - Mentally or physically incapacitated? Probably not (Secs 2.8, 2.13)
- Driver mistook geographic position of train?
 - Thought he was in different block? **Not addressed**
 - Thought he was further along the block? „*Real possibility*“ (Sec 2.8)
- Driver wasn't aware of impending sharp curve
 - misread/misremembered Route Map? **Not addressed**
 - ... or lapsed in understanding route? **Not addressed**
 - ... or left his driving position and missed cues? Possibly (Sec 2.8, also Conclusions 3.2: Underlying Factors 3)

Potential Causes of Failing to Slow 2

- Driver intentionally caused derailment
 - No evidence (Sec 2.8)
- Driver intentionally driving fast
 - and misjudged braking? „*Unlikely*“ (Sec 2.8)
 - and misjudged stability? **Not addressed**
 - Note: DMU has higher CoG than EMU and he drove both
 - Note: He has no other traffic to worry about, just the track geometry

Potential Causes Not Addressed by Report

- Driver mistook geographic position of train?
 - Thought he was in different block?
 - Thought he was further along the block? **Partially addressed only**
- Driver wasn't aware of impending sharp curve
 - misread/misremembered Route Map?
 - ... and lapsed in understanding route?
- Driver intentionally driving fast
 - and misjudged stability?

Mistook Geographic Position 1

- Did he mistake the block and think he was somewhere else than between BO and BA?
 - Signals at BO clearly marked „BO xy“, where x and y are each decimal digits
 - Signal marker boards „very visible“
 - With two drivers in cab, driver driving must call out signal ID when passing and driver not driving must confirm
 - One could conclude it is unlikely that the driver mistook the block he was in
 - Nevertheless, this issue is not addressed in the report:
an incompleteness

Mistook Geographic Position: At BA SPM? 1

- Did he think he was at BA SPM, just before the 110-kph-posted curve? A „*real possibility*“ (Sec 2.8, also Conclusions: 3.2 Underlying Factor 2)
- Consider the facts about the route

Mistook Geographic Position: At BA SPM? 2

- The train had passed no sharp curve after BO
- He would have sensed CTC curve, had CTT traversed it
 - The power car, where the driver is, does not tilt
- The magnet sequence
 - MSM is 2nd magnet after BO
 - BA SPM is 3rd magnet after BO
 - MSM is about 3.5 km from BO SPM
 - BA SPM is about 6.5 km from BO SPM
 - He was only 2.5 minutes from BO SPM
 - BA SPM is somewhere between 4-5 minutes from BO SPM
- The „freedom“ sequence
 - 150-kph SPB gives the driver freedom to full-throttle
 - There are two „freedom“ segments: one before CTC and one after
 - He'd opened up the throttle just once

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Mistook Geographic Position: At BA SPM? 3

- In order for this „*real possibility*“ to have occurred inadvertently, the driver would have had to
 - err in counting magnet alarms
 - err in counting his „freedoms“
 - mistake his 2.5-minute journey since BO SPM for a 4-5-minute period
 - be unaware that he had not sensed the sharp curve at CTC
 - be unaware of his speed profile since BO SPM of having maintained a speed at least 12 kph above that allowed at CTC
 - be unaware of having accelerated continuously under „steady power“ for over 4 km, since the shunt limits/75-kph speed board at BO
- In my judgement, that would constitute a „lapse in concentration“ of significant proportions
- One might well consider it to show cognitive impairment

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Mistook Geographic Position: At BA SPM? 4

- So this „*real possibility*“ implies a multitude of significant lapses, to an extraordinarily high degree
- But the report considers the driver to have been in possession of the appropriate cognitive faculties (Secs 2.8, 2.12, 2.13 as noted)
- So it looks to this reader as though the report almost contradicts itself
 - One cannot speak of a literal contradiction here: these issues concern degrees to which cognitive properties manifest. Better to say **high tension**?
 - That leads us to consider dissolving the *high tension*

Resolving/Dissolving the *High Tension* 1

- One horn
 - The driver suffered a close series of significant cognitive lapses, both continual and punctual, over a period of three minutes or more
 - Neither the „soft“ protection systems (two-driver ops, speed boards, route knowledge and maps) nor the „hard“ protection system (BO SPM, MSM) sufficed to intrude into cognition
- Conclusion
 - The design of the protection systems on the route do not take into account the possibility of such significant lapses.
 - If one concludes that they did occur, protection systems **must** be adapted

Resolving/Dissolving the *High Tension 2*

- The other horn
 - Assume that the driver was indeed in possession at the time of appropriate cognitive faculties (such that a significant ongoing series of lapses likely did not occur)
 - Then he was aware that he was traversing/had traversed a section including a 60-kph restriction at speeds high (indeed, much higher) than 72 kph
 - That is, he was and had been prepared to bust speed limits where he thought it appropriate
- The report does not address this possibility: **another incompleteness** in the report

Observations 1

- Observe that deliberate violation of the speed limit would be enough by itself to explain the accident
- Note that **I am not making the suggestion that this did happen**
 - I am not a policeman; I am not an investigator; I am not a lawyer; I am not expert in the sociology of railwaymen in Australia; <insert appropriate additional disclaimers>
- I am saying that a comprehensive analysis would address it; and that the report didn't do so

Observations 2

- But is this horn of the high tension at all plausible?
 - **Yes, unequivocally.** See Scott Snook's Theory of Practical Drift in his analysis of the Operation Provide Comfort shootdown of two US Army Black Hawk helicopters by USAF F-15 fighter aircraft in the no-fly zone over Northern Iraq in 1994 (*Friendly Fire*, Princeton University Press, Princeton, N.J., 2000)
 - Interpretation of Practical Drift theory here:
 - Tensions between organisational goals
 - Prestigious „high-speed“ service
 - Safety requires low speeds at many points
 - lead to dynamic adaptations of procedures and behavior
 - „Speeding“ by drivers where it is considered to be doable

Observations 3

- The phenomenon whereby agents adapt behavior and procedures to resolve tensions in organisational goals (whether one calls it „practical drift“ or not) is widely recognised
- Some examples
 - „Get-home-itis“: corporate aircraft crews under pressure to take the boss where heshe wants, when heshe wants
 - Corporate aviation is significantly more susceptible to weather-related accidents than commercial aviation
 - Commercial aircraft crews under pressure to maintain schedule and destination
 - Landing at the goal airport, near to time, while conserving fuel

Observations 4

- An example closer to „home“:
 - December 1999 Glenbrook, NSW, rail accident
 - Analysed by Andrew Hopkins (Chs. 2-7 of *Safety, Culture and Risk*, CCH Australia, Sydney, NSW, 2005)
 - Commuter train passed a signal at „halt“...
 - ... after obtaining permission from signaller to do so...
 - ... after signaller indicated informally that track was clear...
 - ... commuter train driver accelerated
 - ... and ran into the rear of the *Indian Pacific* cross-country train that had been waiting at the next (halt) signal while obtaining permission to proceed
 - Hopkins discusses cultural tensions and adaptations to those tensions within NSW rail operations

Observations 5

- Besides ... dare I say this? ... isn't it sometimes just fun to exercise the capabilities of well-designed high-tech equipment?
- Possibly c.f. 1988 Airbus A320, Habsheim, France?
 - Air France pilot attempted to perform „standard“ Airbus airshow-pilot manoeuvre – steep climb-out from low-energy low pass
 - Without having experience with the manoeuvre
 - Without having scoped the airshow airport
 - Without having fulfilled the legal requirements for approval
 - With a plane load of uninformed passengers (illegal!)
 - From/in an unstabilised approach and unstable/unplanned state
 - With far too low engine speed („idle“ power instead of 60% N1)

Observations 6

- The report suggests that the scenario in which the driver was intentionally driving „*to the limit*“ and misjudged braking is „*unlikely*“ (Sec 2.8)
- However, that he misjudged his braking is fact:
 - He applied full brakes 2-3 seconds before derailment
 - That suggests that he felt he needed emergency brakes
 - Full braking is not comfortable for (sleeping?) passengers
 - As far as anyone knows, there was no obstacle on the track to cause such a brake application
 - The full braking occurred at or near the CTC speed board
- Given the previous observations, one wonders which part of this scenario renders it „*unlikely*“, and how?

Unawareness of Impending Curve

- Such unawareness would imply that
 - either the driver was operating under significant cognitive impediment (ruled out: Secs 2.8, 2.13)
 - ... or he overlooked the CTC speed restriction on the Route Map (either through misattention or through not using the Route Map) and had forgotten about it (misapplied his route knowledge)
 - This second potential factor is not considered in the report:
an incompleteness
 - Note that such a phenomenon has been seen already in the *first horn* of the *high tension*

Intentional Speeding

- Considered already as the *second horn* of the *high tension*
 - Reminder: the report does not consider it. This constitutes **an incompleteness** in the report

Failing to Slow: Summary

- The report considers some, but not all, of the causal possibilities of the driver failing adequately to slow
- The causal possibilities that it fails to consider are
 - Mistaking the block
 - Consequences of the scenario of thinking to be at BA-SPM
 - Significant cognitive lapses continuously for over 3 minutes, or
 - Intentionally speeding (or being prepared to do so)
 - Consideration of this scenario calls into question the judgement that scenario of „driving to the limit“ and misjudging braking „unlikely“
 - Unaware of curve/Misapplying Route Map/Knowledge
 - Scenario has much in common with above and analysis is similar
 - Intentional „speeding“
 - ... for understandable, indeed well-studied, sorts of reasons
 - Scenario also considered in above analysis

Issue 2: Adequacy of Protection Systems

Existing Protection Systems

- Route Knowledge & Maps
- Station-protection/mid-section magnets
- Speed boards
- Two drivers

Protection Systems 1: Route Knowledge

- Although route knowledge and competence is trained, training is regarded across many industries as insufficient to eliminate procedural errors fully
 - e.g., see comments above on why driver failed to slow
- Indeed, it may encourage them!
 - Intimate route knowledge may lead to overconfidence in the capabilities of the kit
 - Intimacy with operations may lead to violations of defined procedure
 - particularly to increase „efficiency“ or ameliorate tensions
 - again, as in Snook's Theory of Practical Drift

Protection Systems 2: Warning Magnets

- Positional warning systems of this simple kind are present on most railway systems in the developed world
- They give point-based, relative-positional information, and rely on a driver knowing within the resolution distance (less than or equal to one block) where he/she is
 - The mid-section magnet apparently did not suffice in this case to warn the driver that he needed to reduce speed
 - (something else did, 13-14 seconds later)

Protection Systems 3: Speed Boards

- These are speed-limiting signs, not advance warnings of speed restriction
 - They advise a driver of the current speed limit
 - They do not suffice to warn a driver sufficiently in advance to reduce speed

Protection Systems 4: Two Drivers

- In aviation (Pilot Flying and Pilot Not Flying) two operators can function as a team
 - there are flying tasks and non-flying tasks to perform
 - However, there are few non-driving operational tasks in the cab besides supervision – it is mostly „single driver“
 - Such so-called „supervisory control“ is not always effective
 - This is well-known: see work of Thomas B. Sheridan
 - In air traffic control, supervision has been shown to be helpful
 - In other domains, a „group think“ effect, whereby both parties tend to make the same mistaken assumptions about a state of their operation, can be/is often present (see especially Snook, *op. cit.*, concerning both the pilot-wingman team and the AWACS team)
 - It is not (yet) known in rail operations which mode dominates

Signalling Systems

- Light signals at stations
- Speed boards
- Station markers
 - station signals have reflective nameplates with unique ID
 - station unique-ID: Berajondo is BO; Baffle is BA
 - 2-digit number
 - readable from the cab
 - 2-driver ops requires call-out/confirmation when passing
 - ... when there are two drivers in the cab
- (Milestones? There, but not signals)
 - reflective kilometer markers, but positioned away from the track and do not normally act as cues for the driver)

Existing Protection Systems: Analysis

- Had the driver
 - been aware that he was between BO and BA
 - correlated the MSM alarm with the Route Map and the time as well as his route knowledge
- then the MSM might have sufficed to allow sufficient speed reduction
 - in the accident case (from 111 kph down to say 90 kph)
 - but not in regular operations (from say 120 kph down to 60 kph)
 - and not theoretically (from 150 kph down to 60 kph)
 - Proof follows

Braking from Mid-Section Magnet 1

- The dynamics of braking is as follows
 - Distance mid-section magnet to speed board = **415 m**
 - $S = v_0 \cdot t + a \cdot t^2 / 2 = (v^2 - v_0^2) / 2 \cdot a$
 - @ $a = 1 \text{ m/s}^2$, $v_0 = 150 \text{ kph} \sim 42 \text{ m/s}$, $v = 60 \text{ kph} \sim 17 \text{ m/s}$
 - *braking distance* = 738 m + *reaction distance*
 - @ $a = 1 \text{ m/s}^2$, $v_0 = 120 \text{ kph} \sim 33 \text{ m/s}$, $v = 60 \text{ kph} \sim 17 \text{ m/s}$
 - *braking distance* = 400 m
 - *reaction time* = 2 s
 - *reaction distance* = 2 s x 33 m/s = 66 m
 - *total distance from magnet to 60 kph* = **466 m !**

Braking from Mid-Section Magnet 2

- For the existing situation:
 - @ $a = 1 \text{ m/s}^2$, $v_0 = 111 \text{ kph} \sim 31 \text{ m/s}$, $v = 90 \text{ kph} \sim 25 \text{ m/s}$
 - *braking distance* = 168 m
 - *reaction time* = 2 s
 - *reaction distance* = 2 s x 31 m/s = 62 m
 - *total distance from magnet to 90 kph* = 230 m
- Conclusion: the driver could have slowed the DMU sufficiently to round the CTC curve without derailling, had he
 - had appropriate positional awareness
 - reacted with braking to the mid-section magnet alarm
- But this is not practical for the design of regular operations
 - exact wheel unloading dynamics not known beforehand

Braking from Mid-Section Magnet 3

- Deceleration of 1 m/s^2 is emergency braking
 - Normal braking on, say, the German railway is 0.5 m/s^2
- At normal braking (0.5 m/s^2), the figures are
 - @ $a = 0.5 \text{ m/s}^2$, $v_0 = 150 \text{ kph} \sim 42 \text{ m/s}$, $v = 60 \text{ kph} \sim 17 \text{ m/s}$
 - *braking distance = 1,476 m + reaction distance !*
 - @ $a = 0.5 \text{ m/s}^2$, $v_0 = 120 \text{ kph} \sim 33 \text{ m/s}$, $v = 60 \text{ kph} \sim 17 \text{ m/s}$
 - *total distance from magnet to 90 kph = 866 m !*
 - @ $a = 0.5 \text{ m/s}^2$, $v_0 = 111 \text{ kph} \sim 31 \text{ m/s}$, $v = 90 \text{ kph} \sim 25 \text{ m/s}$
 - *total distance from magnet to 90 kph = **398 m !***
- Normal braking would barely have sufficed !

Braking from Mid-Section Magnet 3

- Conclusion: the mid-section magnet does not suffice to give appropriate operational indication of the approaching speed restriction to 60 kph
- It follows that, in absence of visual clues (this section is always passed at close to midnight by the CTT),
 - either route knowledge plus dead reckoning
 - or a preparatory speed restriction to below 120 kph, in anticipation of further slowing at the MSM
- ... is necessary to achieve the required 60 kph by the CTC SPB

Protections: Summary 1

- Route knowledge + dead reckoning is not reliable to the degree required to avoid all possible procedural errors over the operational life of the CTT
 - equally whether there is a driver team or single driver
 - This human phenomenon is unavoidable
- The speed restriction preparatory to CTC SPB is procedurally ineffective
 - Note this is consistent with intent: speed boards are not intended to guide operations, but to restrict them
 - Either there needs to be an appropriate speed restriction
 - or additional reliable protection mechanisms need to be installed at this point

Protections: Summary 2

- Note that no „soft“ protection (for example, an advance speed restriction, or an advance warning board) would suffice to preclude intentional speeding
- Only a „hard“ protection (ATP, say at an advance speed warning board and again at the MSM) would suffice rigorously to preclude deliberate speeding
- A „firm“ protection - say, data logging and post-trip evaluation - might help (see next slide)

„Firm“ Protection

- It may be that those drivers who might have been tempted to drive faster than posted have now been discouraged from traversing CTC at greater than, say, 90 kph :-)
 - Might one consider this cultural feature a form of „firm protection“? Or is it still „soft“?
- A driving operational-quality assurance program (DOQA) based on full-journey data loggers and (semi-automated) evaluations of each journey might suffice to identify common procedural infelicities (without needing to distinguish between inadvertent and deliberate actions)
 - FOQA (Flight Operational Quality Assurance) is proving its worth for many airlines, including Qantas I believe
 - There is now significant experience with FOQA which could be adapted to rail operations

Conclusion of Protection-System Analysis

- Additional protective mechanisms are required at (at least) CTC to ensure that normal operations can be pursued in darkness
 - even with a speed reduction to 110 kph over this segment
 - with normal braking performance
 - with adherence to all posted speeds
- Possible such mechanisms include
 - advance speed restriction at CTC
 - advance speed warning boards
 - ATP
 - a DOQA program

Protection Systems: Comment

- The analysis has concluded that the existing protection systems cannot have sufficed to ensure that the Cabbage Tree Creek curve would be successfully rounded under all foreseeable circumstances
 - This raises questions for the scope and conclusions of the „comprehensive risk assessment“ and „fully documented safety case“ which established that this line was „suitable for tilt train operations“ (QT/ATSB Report Sec 2.2)
 - One obvious response: of course the line was suitable, in the sense that one can just travel according to whatever procedures maintain the required safety level!
 - But what exactly were/are those procedures?

Conclusions

- This work
 - has performed a WBA of the Berajondo derailment
 - ... and has analysed therefrom the major causal factors identified by the WBA:
 - Possible causes of the driver's failing to slow
 - Adequacy of overspeed protection systems
 - ... and has concluded that
 - the consideration in the accident report of the possible causes of the driver's failing to slow is incomplete
 - the overspeed protection systems in the vicinity of Cabbage Tree Creek are inadequate
- It demonstrates once again the value of performing a WBA

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- www.qantasvacations.com for the picture crossing the creek
- www.traveltrain.com.au for the small route map
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 - www.transport.qld.gov.au/qt/LTASinfo.nsf/index/railsafety_reports_cairns

The End

Thanks for listening!